



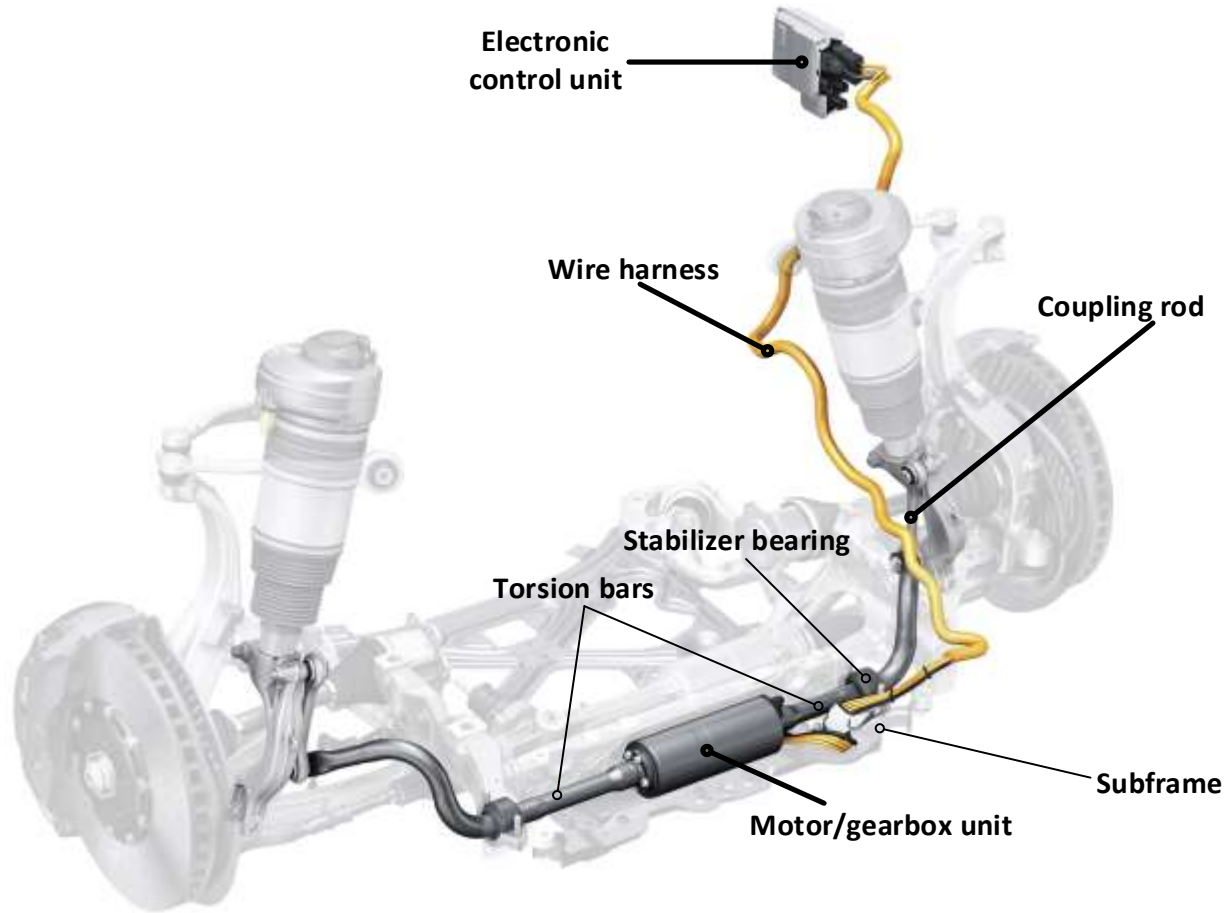
Early Verification and Testing of a Mechatronic Active Roll Control

Dr. Hua Huang | Schaeffler Technologies AG & Co. KG
QTronic User Conference 2019, Berlin

Agenda

- 1 Background and Motivation**
- 2 Virtual Testing with Silver
- 3 Use Case @Schaeffler

intelligent Active Roll Control (iARC)



► iARC system components, integrated in the front axle of an SUV (©Audi, Schaeffler)

Roll control



Active mechatronic roll control

Passive roll stabilization

Comfort



Decoupling: actuator torque front axle $T_{FA} \hat{=} 0$

Agility and sportiness



Understeer $T_{FA} > T_{RA}$

Neutral drivability $T_{FA} = T_{RA}$

Oversteer $T_{FA} < T_{RA}$

Safety

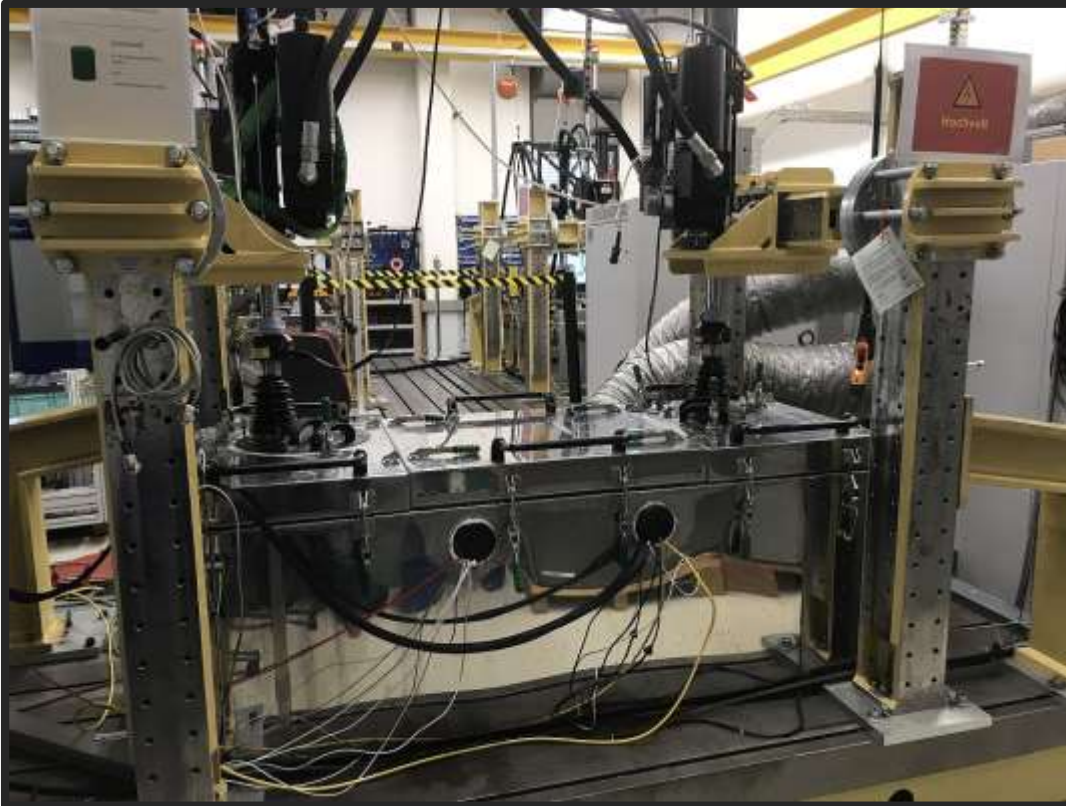


Active mechatronic roll control

Passive roll stabilization

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System Functional Test: Status and Challenges



Test Environment

- ▶ Target signals: Test profiles
- ▶ External disturbances at coupling rods: 2x hydraulic pulser system
- ▶ Vehicle/Chassis communication: Restbus simulation
- ▶ Supply voltage: 36V / 48V / 52V
- ▶ Ambient temperature: -30°C / 23°C / 80°C

Challenges

- ▶ Higher cost (compared with virtual testing)
- ▶ Bug-fix of unexpected errors brings more time consuming on test bench
- ▶ Test scheduling depends on the availability of the bench

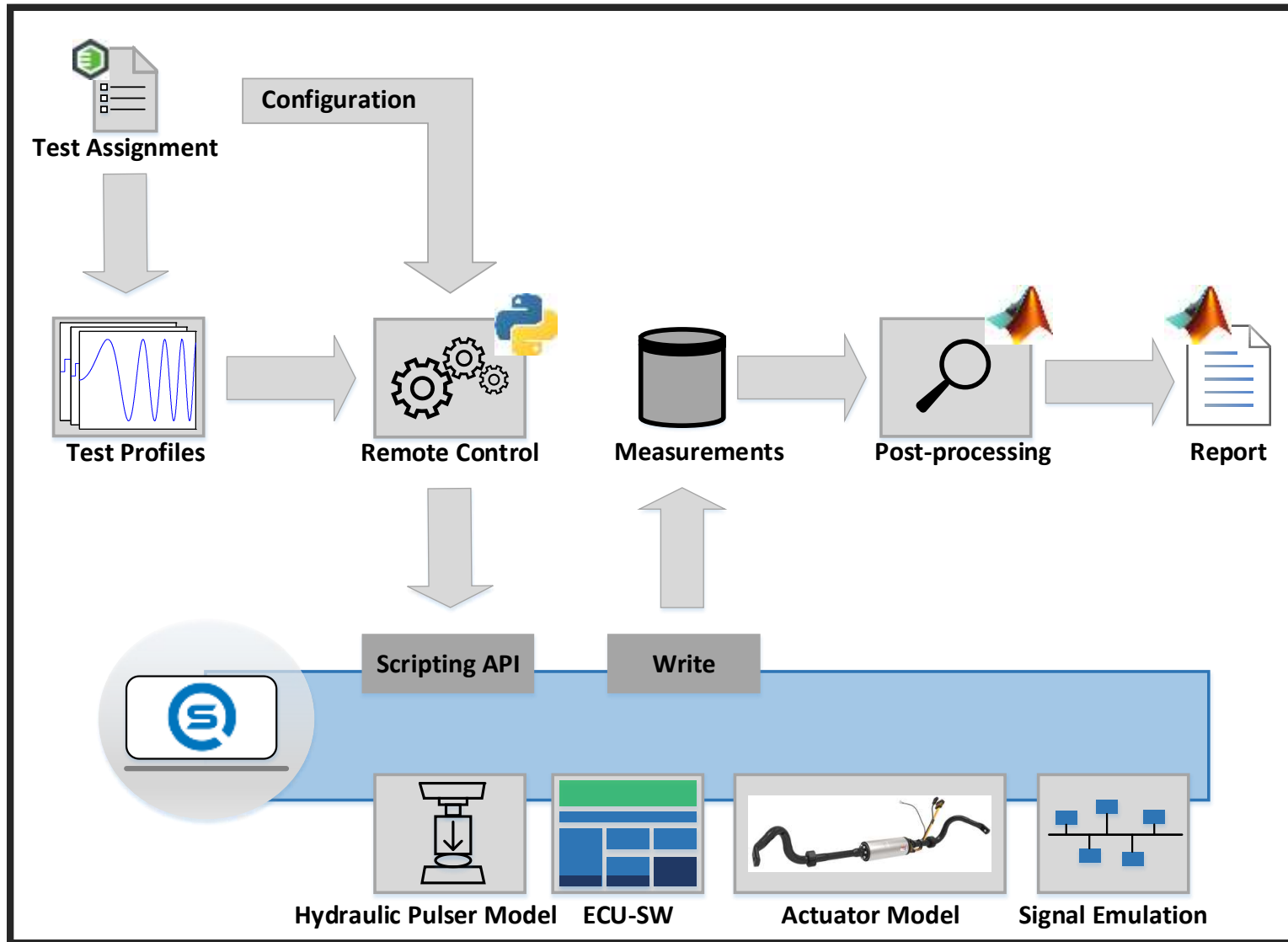
Motivation

- ▶ Virtual testing on PC
 - Reduce cost on test bench
 - Increase the test coverage
 - Early verification and testing

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Workflow of Virtual Testing



- ▶ Virtual simulation platform in Silver
- ▶ Test assignments are synchronized with database, i.e. PTC Integrity
- ▶ Virtual simulation platform is parameterized by software release, parameter container, actuator type and so on
- ▶ Post-processing: e.g. boundary values
- ▶ Test report shown in the end with “pass/fail” results

Virtualization

Real object



Hydraulic pulser system



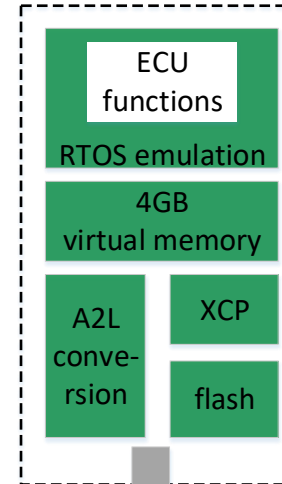
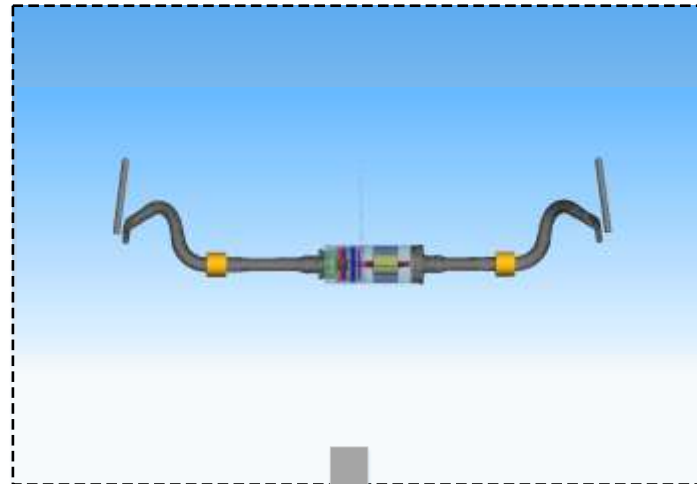
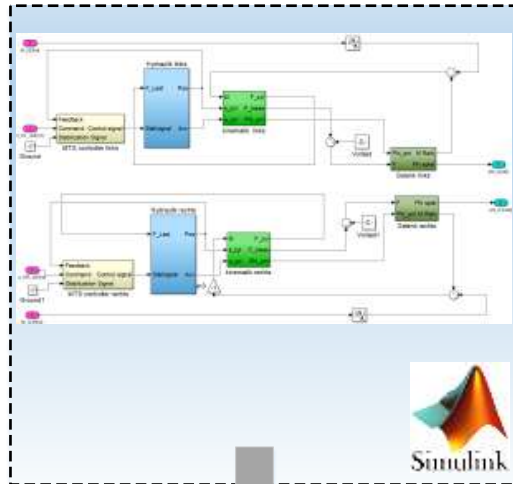
iARC

virtualization

virtualization

virtualization

Modelling



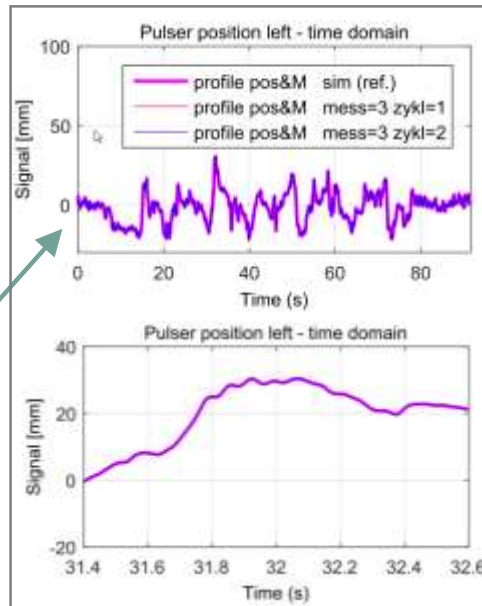
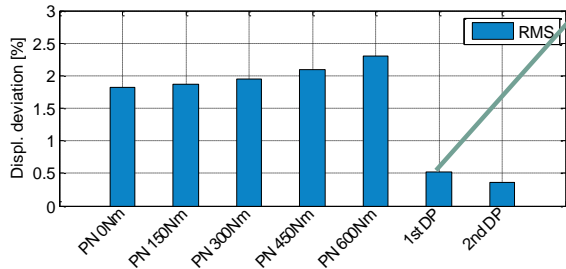
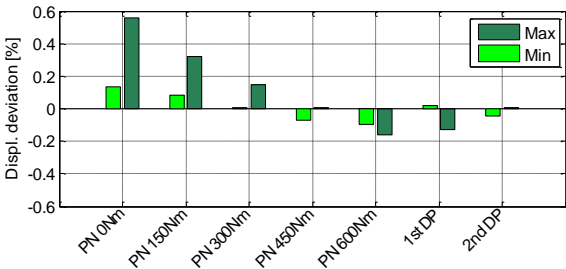
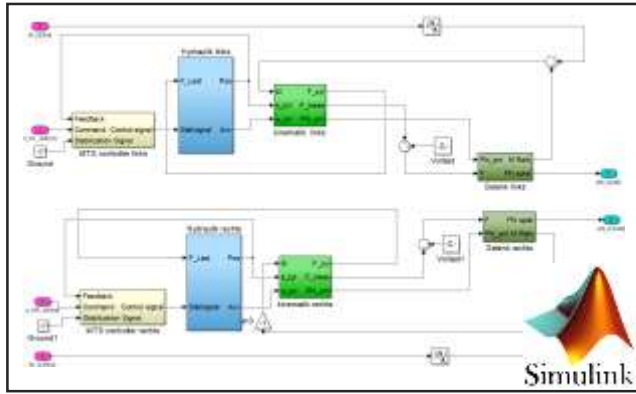
Simulation platform



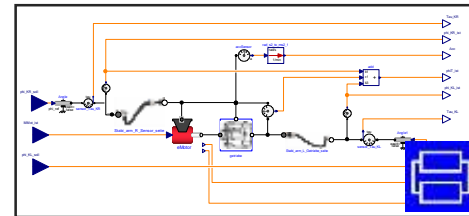
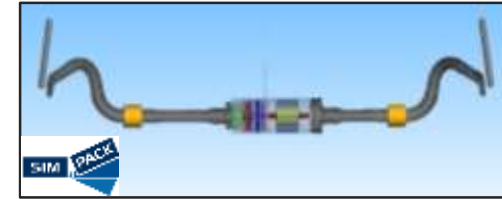
Silver

Virtualization of Physical Models

► Hydraulic pulser system



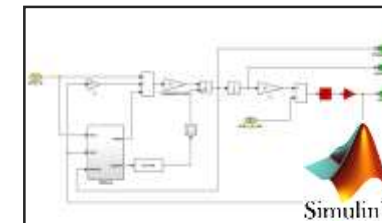
► iARC (actuator component)



Basic

Intermediate

Advanced



Virtualization of ECU-SW

Options

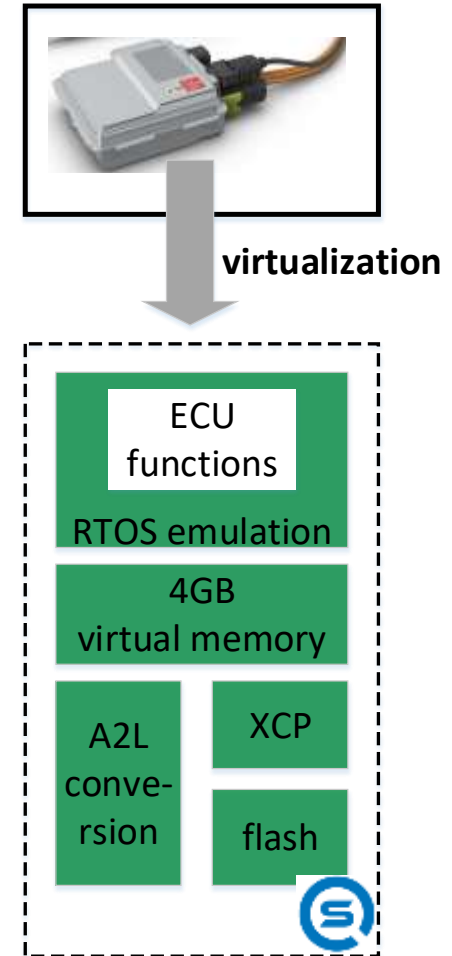
- ▶ MATLAB/Simulink modules in MiL (Model-in-the-Loop)
- ▶ C code in SiL (Software-in-the-Loop)
- ▶ Delivered Hex file (binary containing data and program code)

Status

- ▶ SW is developed together with another supplier
- ▶ Hex file is delivered from SW department and verified against specification
- ▶ Use the identical SW as the one on test bench

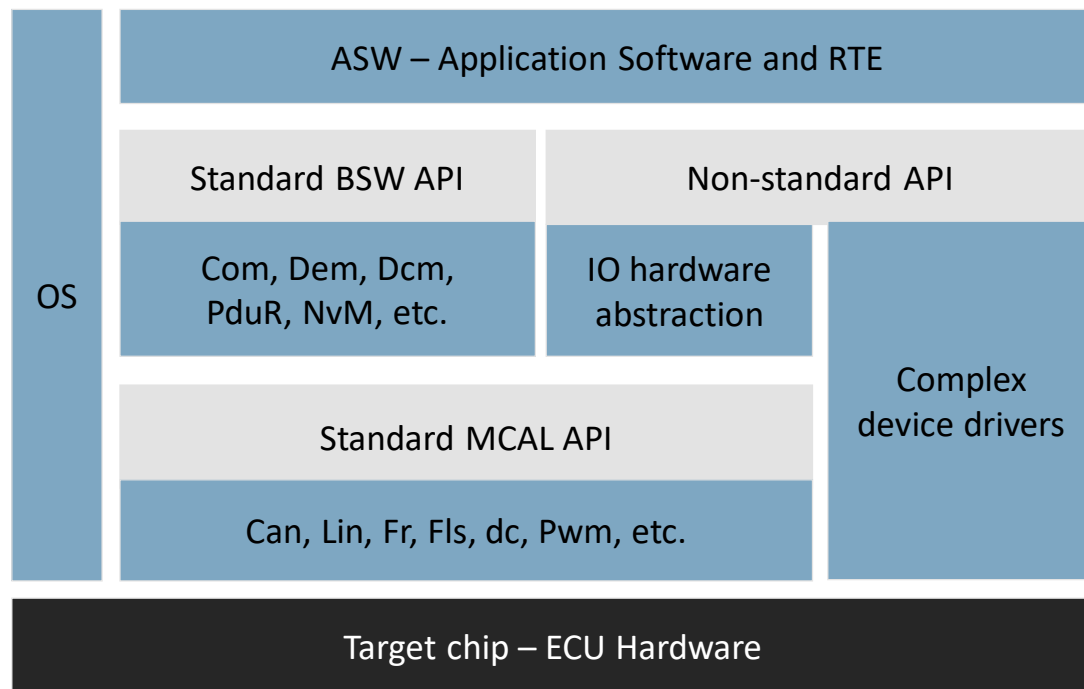
Virtualization

- ▶ Chip simulation

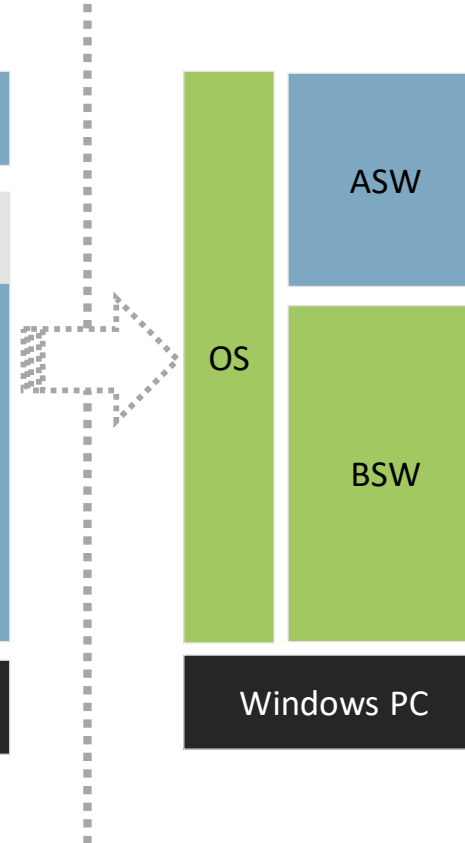


Virtual ECU with Chip Simulation

ECU (here: Autosar)



virtualization



■ Original software
 ■ Emulated software
 ■ Interface
 ■ Hardware

Principle of chip simulation

- ▶ Mapping the instruction set of the target processor to the instruction set of the host processor on PC

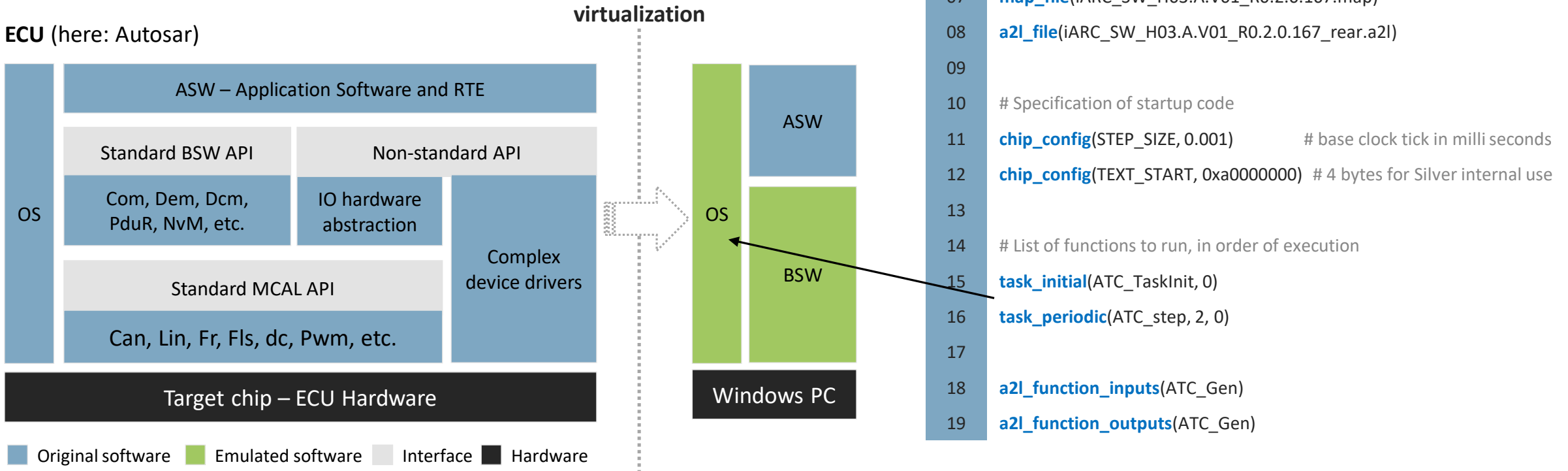
Use case of chip simulation

- ▶ Only application SW
- ▶ Basic SW is verified in HiL (Hardware-in-the-Loop)

Virtual ECU with Chip Simulation

Needed files

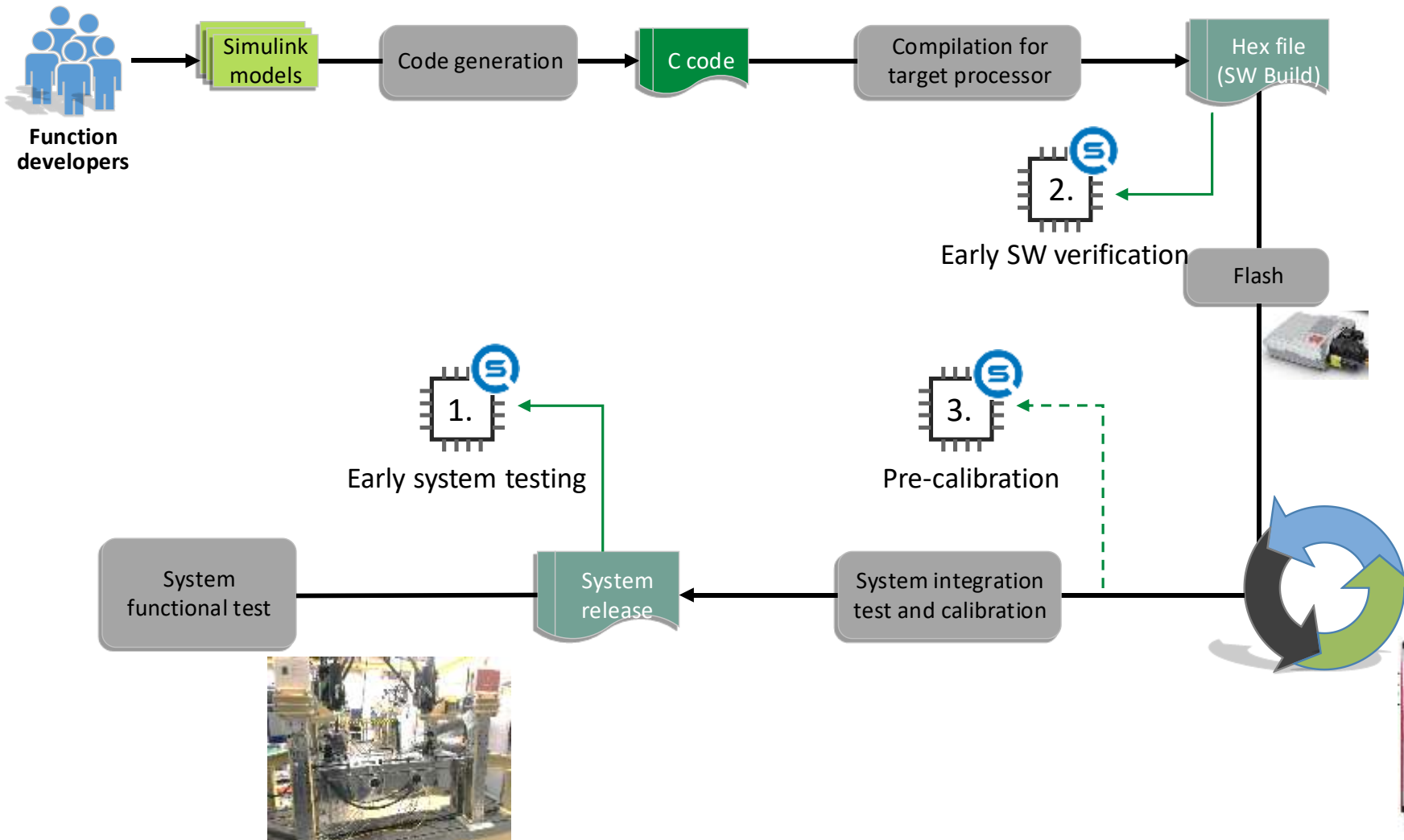
- ▶ **Hex file:** Program code and data of the functions to run
- ▶ **A2L file:** Describes the inputs, outputs (MEASUREMENT elements) and parameters (CHARACTERISTIC and shared AXIS_PTS elements)
- ▶ **MAP file:** Maps function names to ECU memory addresses
- ▶ **DCM file (for calibration):** Calibration data to be flashed



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Early Software Verification and System Testing



1. Early system testing

- ▶ Functional testing in system context

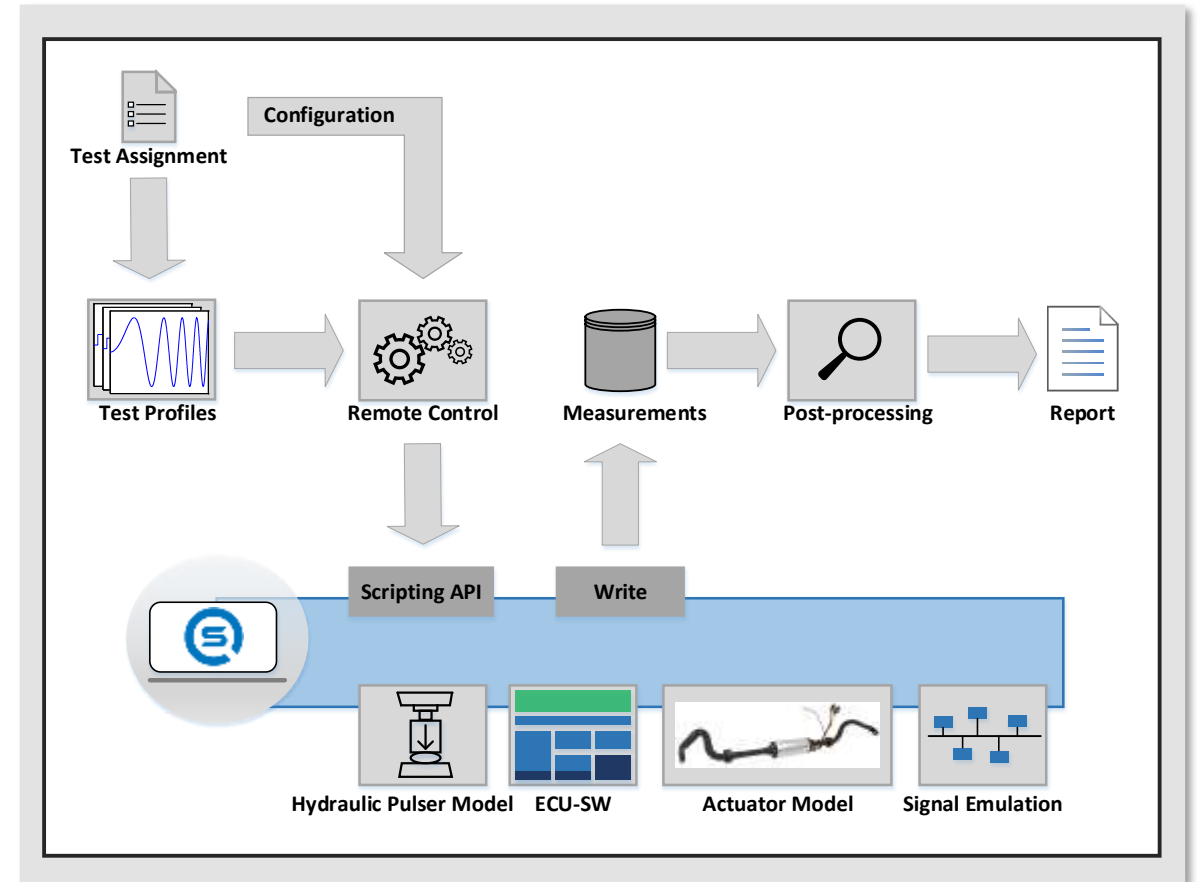
2. Early software verification

- ▶ When SW-Build is deployed
- ▶ Move selected tests from HiL
- ▶ Component testing

3. Pre-calibration

Status Quo

- 1 46 % IDs of system functional test can be verified in virtual environment
- 2 Virtual testing has a good correlation with measurements
- 3 Enlarge test strategy in a cost-effective way
- 4 Has been established for more than one project, and is also planned for other chassis mechatronic systems
- 5 Continuing improvement of physical models to increase test scenarios



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